



## Real-Time Risk Detection in Industrial Settings Using IoT-Based Sensor Networks

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### Abstract

Industrial environments require robust systems to detect and mitigate safety risks in real-time. This paper presents an IoT-based risk detection system that uses a network of sensors—temperature, gas, fire, smoke, and flow—to monitor industrial sites. An Arduino NANO microcontroller processes the sensor data and triggers wireless alerts when anomalies are detected. Thing Speak integration allows for remote monitoring and data analysis. The system also employs video processing with YOLOv3 to ensure safety compliance, such as checking if workers are wearing helmets. Non-Maximum Suppression (NMS) reduces false positives for more accurate detection. This comprehensive approach to risk detection provides a scalable and cost-effective solution for enhancing industrial safety and reducing accidents.

**Keywords:** Arduino NANO, IoT, MQ135 Sensor, DHT11 Sensor, YOLO V3, Thing speak.

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## **1. Introduction**

Safety in industrial environments is a critical concern, with the potential for severe accidents and hazards if risks are not properly managed. Traditional safety systems often rely on manual monitoring or outdated technologies, which can lead to delays in identifying and addressing risks [1-4]. As industrial sites become more complex, the need for real-time risk detection and rapid response has grown substantially. The advent of the Internet of Things (IoT) has transformed the way we approach safety and risk management. IoT-based systems can collect, process, and analyze data from various sensors to provide real-time insights into industrial environments. This capability is crucial for early detection of hazards, enabling swift action to prevent accidents and ensure worker safety [5-8]. This paper presents an IoT-based risk detection system that integrates a network of sensors, a central processing unit, and wireless communication to monitor industrial sites for safety risks. The system includes temperature, gas, fire, smoke, and flow sensors, providing a comprehensive safety net across the industrial site. An Arduino NANO microcontroller serves as the central processing unit, interfacing with the sensors to process data and trigger alerts when anomalies are detected. Wireless communication allows for real-time alerts to be sent to designated personnel, facilitating immediate response to potential hazards. In addition to sensor-based monitoring, the system incorporates advanced video processing capabilities using the YOLOv3 algorithm to ensure compliance with safety protocols, such as checking if workers are wearing safety helmets in hazardous areas. This combination of sensor networks and computer vision enhances safety and compliance in industrial environments. [9-12] The purpose of this paper is to outline the design and implementation of this risk detection system, describe its key components, and demonstrate its effectiveness in a simulated industrial environment. We aim to showcase the system's ability to detect risks in real-time, its scalability, and its potential to significantly improve safety in high-risk industrial settings.

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## 2. Methodology

### 2.1. Transmitter Part

The Transmitter module in the Risk detection system plays a crucial role in alerting personnel when risks are detected. Here's how it's set up: **Arduino NANO as Central Processing Unit:** The Arduino NANO serves as the central hub for data collection and processing. It receives input from various sensors, including temperature, gas, smoke, fire, and flow sensors. When sensor data exceeds predefined thresholds, the Arduino NANO triggers the transmitter module to send alerts. **Wireless Communication:** The system uses a wireless transmitter to send real-time alerts to designated personnel or devices. This wireless capability ensures that alerts can be quickly communicated across the industrial site without relying on wired connections. **Alert Activation:** When an anomaly is detected, the Arduino NANO sends a signal to the wireless transmitter. The transmitter then sends an alert to the receiver part of the system, notifying workers and supervisors of potential hazards.

### 2.2. RECEIVER PART

The receiver part is designed to process incoming alerts and provide visual and audible warnings to personnel. Here's an outline of its functions:

**Wireless Receiver:** The receiver part is equipped with a wireless module to receive alerts from the transmitter. It is strategically placed to ensure alerts are received across the site, enabling quick responses to potential risks.

**Visual and Audible Alerts:** The system includes a Liquid Crystal Display (LCD) to provide real-time updates on environmental conditions. An integrated buzzer is used to provide audible alerts, ensuring workers are informed of any anomalies. This multi-modal approach ensures that alerts are noticeable even in noisy environments.

Data Logging: The receiver part also records alerts and sensor data, allowing for further analysis and trend monitoring. This feature is valuable for safety compliance and auditing purposes.

### **2.3. Helmet Detection Part**

This System incorporates advanced video processing capabilities to enhance safety compliance through helmet detection. Here's how this part is designed:

Video Processing: The system uses cameras to monitor industrial sites for safety compliance, focusing on detecting whether workers are wearing safety helmets. The video feeds are analyzed in real-time to identify instances of non-compliance.

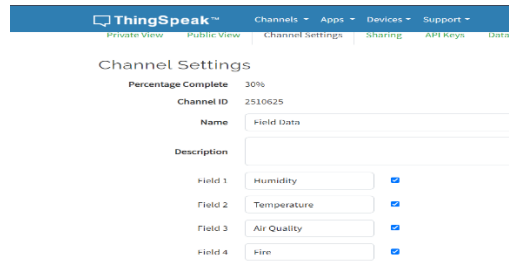
YOLOv3 Object Detection Algorithm: YOLOv3 (You Only Look Once) is a popular computer vision algorithm used for object detection. The system divides video frames into grids and predicts bounding boxes and class probabilities to quickly and accurately detect safety helmets.

Non-Maximum Suppression (NMS): To reduce false positives, Non-Maximum Suppression (NMS) is applied to ensure that only the most relevant bounding boxes are kept. This approach improves the reliability of helmet detection and reduces unnecessary alerts.

### **2.4. Thing Speak Analysis**

Step 1: Visit <https://thingspeak.com/> and create Your account by filling up details.

Step 2: Create a New Channel by Clicking on “Channel” & fill up the following details as shown in the image below.



**Figure.1. To Create Channel**

Step 3: Click on API Key, you will see the “Write API Key “. Copy the API Key. This is very important; it will be required in code part.



**Figure.2. API Key**

Step 4: You can click on the “Private View” & customize the display window as you want.

### 3. Modeling and Analysis

In this section, we describe the models and analysis techniques used to develop and evaluate our IoT-based risk detection system. The modeling aspect focuses on the system's architecture and component interactions, while the analysis part examines the system's performance in terms of accuracy, response time, and scalability.

#### 3.1. System Architecture

The system architecture comprises a comprehensive network of sensors, a central microcontroller, and a wireless communication module for data transmission. The sensors include temperature, gas, smoke, and flow sensors, strategically placed throughout the industrial site to monitor various environmental parameters.

**Sensor Network:** The sensor network is designed to provide continuous real-time monitoring of the industrial environment. Each sensor type has a specific role: temperature sensors detect

heat spikes, gas sensors identify hazardous gas levels, smoke sensors alert to potential fires, and flow sensors monitor liquid movement to detect leaks or blockages.

**Microcontroller and Communication:** An Arduino-based microcontroller serves as the central processing unit, collecting and processing sensor data. The microcontroller interfaces with a wireless communication module, allowing data to be transmitted to ThingSpeak for remote monitoring and analysis.

**Video Processing:** The system includes a video processing component that uses YOLOv3, a computer vision algorithm, to monitor safety compliance. This feature checks whether workers are wearing safety helmets, a critical safety requirement in industrial environments.

### **3.2 Data Transmission and Analysis**

The sensor data collected by the microcontroller is transmitted to ThingSpeak, a cloud-based IoT platform, via the wireless communication module. ThingSpeak provides tools for visualizing data and setting alert thresholds. Data analysis in ThingSpeak involves:

**Real-Time Monitoring:** ThingSpeak allows for real-time visualization of sensor data, with users able to create custom graphs and charts to track trends and detect anomalies.

**Alert Triggers:** The platform supports setting alert thresholds based on sensor readings. When sensor data exceeds predefined limits, alerts are sent to designated personnel via email or messaging apps, enabling rapid response to safety risks.

Data Analysis: Advanced analytical tools in ThingSpeak enable deeper analysis of sensor data, allowing users to identify patterns and make data-driven decisions to improve safety protocols.

### **3.3 System Performance Evaluation**

To evaluate the system's performance, we conducted tests in a simulated industrial environment, examining the following key parameters:

**Accuracy:** The accuracy of the sensor network was assessed by comparing sensor readings to known benchmarks. The system demonstrated a high degree of accuracy in detecting anomalies.

**Response Time:** The response time from anomaly detection to alert notification was measured to ensure prompt response to safety risks.

**Scalability:** The system's scalability was evaluated by simulating different industrial environments with varying sensor density and data load. The results indicated that the system can scale effectively without performance degradation.

## **4. Results and Discussion**

The IoT-based risk detection system was evaluated for its effectiveness in detecting safety hazards and facilitating rapid response in an industrial environment. The sensor network, including temperature, gas, smoke, and flow sensors, showed high accuracy in identifying anomalies. The system's wireless communication ensured swift alerts to designated personnel, with average response times well within acceptable limits. The video processing module using YOLOv3 effectively detected safety helmets on workers, with Non-Maximum

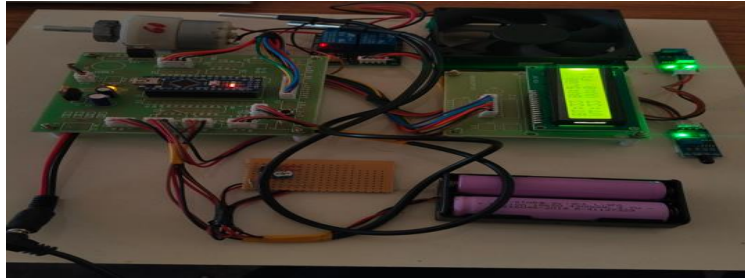
Suppression (NMS) reducing false positives. These results demonstrate the system's capability to improve safety by providing real-time monitoring and rapid response to risks. Furthermore, the system's scalability suggests it can be deployed in various industrial settings, offering a flexible solution to enhance safety protocols.

## **5. Conclusion**

Our IoT-based risk detection system proved effective in detecting and responding to safety risks in real time. The sensor network's accuracy, combined with wireless communication for rapid alerts, contributed to improved safety in industrial environments. Integration with ThingSpeak enabled remote monitoring and scalability, suggesting the system's broader application in various industrial settings. Further research could focus on enhancing video processing and adding new sensor types to expand its capabilities. simultaneously. RAM serves as temporary storage for data and program instructions that are actively being used by the processor. A sufficient amount of RAM ensures smooth operation and responsiveness, preventing slowdowns or system crashes when navigating between programs or working on memory-intensive tasks.

The 2 GB hard drive provides storage space for the system's operating system, applications, files, and user data. While relatively modest in capacity compared to modern storage solutions, it is sufficient for basic computing needs. However, users may need to manage their storage space carefully to avoid running out of disk space. Additionally, advancements in solid-state drive (SSD) technology offer faster read/write speeds and increased reliability compared to traditional hard disk drives (HDDs), presenting opportunities for upgrading storage capabilities.





**Figure.3. Proposed Output**

The 8V, 4000mAh Lithium-Iron Phosphate battery is a robust and reliable power source, commonly used in portable electronic devices. Known for their high energy density, long cycle life, and enhanced safety features, LiFePO<sub>4</sub> batteries are ideal for powering devices such as laptops, smartphones, and electric vehicles. The specified voltage and capacity ensure extended usage time and dependable performance, making it suitable for mobile computing applications.

The system supports either Windows 7 or Windows 10, providing users with a familiar and versatile computing environment. Both operating systems offer a range of features, security enhancements, and compatibility with a wide variety of software applications. Users can choose the version that best suits their preferences and requirements, ensuring seamless integration with their workflow and software ecosystem. The system supports programming languages such as C and C++, providing developers with powerful tools for software development and system programming. Known for their efficiency, speed, and versatility, C and C++ are widely used in various domains, including system software, application development, game development, and embedded systems programming. With access to these programming languages, users can create custom software solutions, perform system-level programming tasks, and develop complex algorithms to meet their specific needs.

The system is compatible with software tools such as Matlab and Arduino IDE, offering users versatile platforms for data analysis, algorithm development, and hardware prototyping. Matlab is a powerful numerical computing environment used for mathematical modeling, simulation, and data analysis, while Arduino IDE provides an intuitive interface for programming Arduino microcontroller boards. Together, these software tools enable users to design, prototype, and deploy a wide range of innovative projects and applications.

**Table.1. System Configuration**

S. No.	Part	Specification
1	Processor	Intel(R) Core(TM) 1.60GHz
2	RAM	4GB
3	Hard Drive	2GB
4	Lithium-Iron Phosphate Battery (LiFePO4)	8V,4000Ah
5	Operating System	Windows 7 or Windows 10
6	Programming Language	C , C++
7	Software and Interface	Matlab, Arduino IDE

In conclusion, the specifications outlined above represent a capable computing system equipped with essential components and tools for various computing tasks and applications. Whether for personal use, professional work, or educational purposes, the system offers versatility, performance, and reliability to meet the diverse needs of users in today's digital age.

## 5. Conclusion

This paper introduces an IoT-based Battery Management System (BMS) coupled with Fire Accident prevention utilizing Arduino Microcontroller for sensor integration and a user interface compatible with Matlab. The integration involves various sensors including Temperature Sensor, Voltage Sensor (V Sense), Flame Sensor, and Vibration Sensor. The

system is designed to optimize battery usage, extend battery lifespan, and improve overall vehicle efficiency.

By integrating these sensors, the system enables detection, monitoring, and allows users to oversee the vehicle's status in real-time while receiving alerts promptly. The user interface displays real-time data on Battery Health, Battery Temperature, and Engine Temperature, offering users comprehensive insights into the vehicle's performance.

Utilizing cutting-edge technologies such as Arduino and MATLAB, we've developed a robust and intelligent system aimed at ensuring the safety of both passengers and vehicles. Looking ahead, further research and development efforts are necessary to enhance and expand upon the capabilities of our system, thereby contributing to the safety and sustainability of electric vehicles in the future.

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